

The Particle-In-Cell (PIC) simulation of plasmas

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Plasma Physics via Computer Simulation C. K. Birdsall & A. B. Langdon



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Computational Electrodynamics A.Taflove



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Cosmology



source: K. Heitmann, Argonne National Lab

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Space propulsion (Plasma thruster)



source: Gauss Center for Supercomputing

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Laser plasma interaction



source: SMILEI dev-team

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Space propulsion (Plasma thruster)



source: Gauss Center for Supercomputing

Laser plasma interaction



- Conceptually simple
- Efficiently implemented on (massively) parallel super-computers

source: SMILEI dev-team





$\begin{aligned} & \mathbf{E} \text{lectromagnetic Field} \\ & \nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0} & \partial_t \mathbf{E} = -\frac{1}{\epsilon_0} \mathbf{J} + c^2 \nabla \times \mathbf{B} \\ & \nabla \cdot \mathbf{B} = 0 & \partial_t \mathbf{B} = -\nabla \times \mathbf{E} \end{aligned}$



Ist Remark

Normalization: the Vlasov-Maxwell (relativistic) description provides us with a set of natural units

Plasma			
$\partial_t f_s + \frac{\mathbf{p}}{m_s \gamma} \cdot \nabla f_s + \mathbf{F}_L \cdot \nabla_\mathbf{p} f_s = 0$			
Electromagnetic Field			
$\nabla \cdot \mathbf{E} = \boldsymbol{\rho}$	$\partial_t \mathbf{E} = -\mathbf{J} + \nabla \times \mathbf{B}$		
$\nabla \cdot \mathbf{B} = 0$	$\partial_t \mathbf{B} = - abla imes \mathbf{E}$		

Velocity	С
Charge	e
Mass	m_e
Momentum	m_e
Energy, Temperature	$m_e c$
Time	ω_r^{-1}
Length	c/ω
Number density	n_r =
Current density	ecr
Pressure	m_e
Electric field	m_e
Magnetic field	m_{e}
Poynting flux	m_e
	4

С c^2 r' $= \epsilon_0 \, m_e \, \omega_r^2 / e^2$ n_r $c^2 n_r$ $c \omega_r / e$ $\omega_r/e c^3 n_r/2$

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	Velocity	С
Plasma	Charge	e
	Mass	m_e
$\partial_t f_s + \frac{\mathbf{p}}{\mathbf{p}} \cdot \nabla f_s + \mathbf{F}_L \cdot \nabla_{\mathbf{p}} f_s = 0$	Momentum	$m_e c$
$m_s\gamma$ $m_s\gamma$	Energy, Temperature	$m_e c^2$
	Time	ω_r^{-1}
	Length	c/ω_r
Electromagnetic Field	Number density	$n_r = \epsilon_0 m_e \omega_r^2 / e^2$
$\nabla \mathbf{D} = \mathbf{D} \mathbf{D} \mathbf{D}$	Current density	$e c n_r$
$\nabla \cdot \mathbf{E} = \boldsymbol{\rho} \qquad \partial_t \mathbf{E} = -\mathbf{J} + \nabla \times \mathbf{B}$	Pressure	$m_e c^2 n_r$
$\nabla \cdot \mathbf{B} = 0 \qquad \partial_t \mathbf{B} = -\nabla \times \mathbf{E}$	Electric field	$m_e c \omega_r / e$
	Magnetic field	$m_e \omega_r / e$
	Poynting flux	$m_e c^3 n_r / 2$

The value of ω_r is not defined a priori, and acts as a scaling factor.

The Particle-In-Cell method integrates Vlasov Equation along the trajectories of so-called *quasi-particles*

Vlasov Eq. is a **partial differential equation** (PDE) in Ns+Nv phase-space: $\partial_t f_s + \frac{\mathbf{p}}{m_s \gamma} \cdot \nabla f_s + \mathbf{F}_L \cdot \nabla_{\mathbf{p}} f_s = 0$

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Direct integration (Vlasov codes) has tremendous computational cost!

The **PIC ansatz** consists in decomposing the distribution fct: $f_s(t, \mathbf{x}, \mathbf{p}) = \sum_{p=1}^{N} w_p S(\mathbf{x} - \mathbf{x}_p(t)) \,\delta(\mathbf{p} - \mathbf{p}_p(t))$

Shape-function Dirac-distribution

The Particle-In-Cell method integrates Vlasov Equation along the trajectories of so-called *quasi-particles*

Injecting this ansatz in Vlasov Eq., multiplying by ${\bf p}$ and integrating over all momenta ${\bf p}$

$$\sum_{p=1}^{N_s} w_p \frac{\mathbf{p}_p}{m_s \gamma_p} \mathbf{p}_p \cdot \left[\partial_{\mathbf{x}_p} S(\mathbf{x} - \mathbf{x}_p) + \partial_{\mathbf{x}} S(\mathbf{x} - \mathbf{x}_p) \right] \\ + \sum_{p=1}^{N_s} w_p S(\mathbf{x} - \mathbf{x}_p) \left[\partial_t \mathbf{p}_p - q_s \left(\mathbf{E} + \mathbf{v}_p \times \mathbf{B} \right) \right] = 0$$

Let us now integrate in space:

$$\sum_{p=1}^{N_s} w_p \frac{\mathbf{p}_p}{m_s \gamma_p} \mathbf{p}_p \cdot \int d\mathbf{x} \left[\partial_{\mathbf{x}_p} S(\mathbf{x} - \mathbf{x}_p) + \partial_{\mathbf{x}} S(\mathbf{x} - \mathbf{x}_p) \right] \\ + \sum_{p=1}^{N_s} w_p \int d\mathbf{x} S(\mathbf{x} - \mathbf{x}_p) \left[\partial_t \mathbf{p}_p - q_s \left(\mathbf{E} + \mathbf{v}_p \times \mathbf{B} \right) \right] = 0$$

Finally leading to solving for all p: $\partial_t \mathbf{p}_p = q_s \left(\mathbf{E}_p + \mathbf{v} \times \mathbf{B}_p \right)$ with $(\mathbf{E}, \mathbf{B})_p \equiv \int d\mathbf{x} \left(\mathbf{E}, \mathbf{B} \right) (\mathbf{x}) S(\mathbf{x} - \mathbf{x}_p)$

If one does things in a smart way, only Maxwell-Ampère & Maxwell-Faraday Eqs. need to be solved

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Take the divergence of Maxwell-Ampère's Eq. :

$$\nabla \cdot (\partial_t \mathbf{E} + \mathbf{J} = \nabla \times \mathbf{B})$$

$$\Leftrightarrow$$

$$\partial_t \nabla \cdot \mathbf{E} + \nabla \cdot \mathbf{J} = 0$$

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If at time t=0, Poisson & Gauss Eqs. are satisfied, and if current deposition is made in a way that conserve charge, then solving only Maxwell-Ampère & Maxwell-Faraday ensures that both Eqs. remain satisfied at later time.





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- 4) add any (user defined) external fields provided they are divergence-free





Gather fields at particle position $[\mathbf{E}, \mathbf{B}]
ightarrow [\mathbf{E}_p, \mathbf{B}_p]$



Gather fields at particle position $[\mathbf{E}, \mathbf{B}] \rightarrow [\mathbf{E}_p, \mathbf{B}_p]$

Push all particles

$$\forall p \quad d_t \mathbf{u}_p = \frac{q_s}{m_s} \mathbf{F}_L$$
$$d_t \mathbf{x}_p = \mathbf{u}_p / \gamma_p$$



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Project current densities on grid*

 $[\mathbf{x}_p, \mathbf{p}_p] \to [\rho, \mathbf{J}]$

* using a charge conserving scheme



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Solve Maxwell's Eqs. $\partial_t \mathbf{E} = -\mathbf{J} + \nabla \times \mathbf{B}$ $\partial_t \mathbf{B} = -\nabla \times \mathbf{E}$

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The Particle-In-Cell loop



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Outlines

- Numerical approach: how to build up your PIC code
- Parallelization: getting ready for the super-computers
- Additional modules: beyond the collisionless plasma
- Some physics highlights: what you can do with a PIC code

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$$(\mathbf{E}, \mathbf{B})_p \equiv \int d\mathbf{x} \, (\mathbf{E}, \mathbf{B})(\mathbf{x}) \, S(\mathbf{x} - \mathbf{x}_p)$$

$$\hat{s}^{(0)}(x) = \Delta x \,\delta(x),$$

$$\hat{s}^{(1)}(x) = \begin{cases} 1 \text{ if } |x| \leq \frac{1}{2} \,\Delta x, \\ 0 \text{ otherwise,} \end{cases}$$

$$\hat{s}^{(2)}(x) = \begin{cases} \left(1 - \left|\frac{x}{\Delta x}\right|\right) \text{ if } |x| \leq \Delta x, \\ 0 \text{ otherwise,} \end{cases}$$

$$\hat{s}^{(3)}(x) = \begin{cases} \frac{3}{4} \left[1 - \frac{4}{3} \left(\frac{x}{\Delta x}\right)^2\right] \text{ if } |x| \leq \frac{1}{2} \,\Delta x, \\ \frac{9}{8} \left(1 - \frac{2}{3} \left|\frac{x}{\Delta x}\right|\right)^2 \text{ if } \frac{1}{2} \,\Delta x < |x| \leq \frac{3}{2} \,\Delta x, \\ 0 \text{ otherwise,} \end{cases}$$

$$\hat{s}^{(4)}(x) = \begin{cases} \frac{2}{3} \left[1 - \frac{3}{2} \left(\frac{x}{\Delta x}\right)^2 + \frac{3}{4} \left|\frac{x}{\Delta x}\right|^3\right] \text{ if } |x| \leq \Delta x, \\ \frac{4}{3} \left(1 - \frac{1}{2} \left|\frac{x}{\Delta x}\right|\right)^3 \text{ if } \Delta x < |x| \leq 2 \,\Delta x, \\ 0 \text{ otherwise.} \end{cases}$$



otherwise.

























$$\mathbf{u}_m = \mathbf{u}_p^{(n-\frac{1}{2})} + \frac{q_s}{m_s} \frac{\Delta t}{2} \mathbf{E}_p$$





$$\mathbf{u}_{m} = \mathbf{u}_{p}^{\left(n - \frac{1}{2}\right)} + \frac{q_{s}}{m_{s}} \frac{\Delta t}{2} \mathbf{E}_{p}$$
$$\mathbf{u}_{p} = \mathbf{u}_{p}^{\left(n - \frac{1}{2}\right)} + \frac{q_{s}}{m_{s}} \Delta t \,\mathcal{M}(\mathbf{B}_{p}) \,\mathbf{u}_{m}$$





$$\mathbf{u}_{m} = \mathbf{u}_{p}^{(n-\frac{1}{2})} + \frac{q_{s}}{m_{s}} \frac{\Delta t}{2} \mathbf{E}_{p}$$
$$\mathbf{u}_{p} = \mathbf{u}_{p}^{(n-\frac{1}{2})} + \frac{q_{s}}{m_{s}} \Delta t \,\mathcal{M}(\mathbf{B}_{p}) \,\mathbf{u}_{m}$$
$$\mathbf{u}_{p}^{(n+\frac{1}{2})} = \mathbf{u}_{p} + \frac{q_{s}}{m_{s}} \frac{\Delta t}{2} \mathbf{E}_{p}$$



Charge-conserving current deposition scheme are available among which Esirkepov's is 'most' popular



Esirkepov, Comp. Phys. Comm. 135, 144 (2001)

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In ID, current deposition is easily done directly from charge conservation: $\partial_x J_x = -\partial_t \rho$ while other component are 'directly' projected onto the grid (see interpolation)

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In 2D & 3D, Esirkepov's method allows to conserve charge (within machine presicion)



$$(J_{x,p})_{i+\frac{1}{2},j}^{(n+\frac{1}{2})} = (J_{x,p})_{i-\frac{1}{2},j}^{(n+\frac{1}{2})} + q_s w_p \frac{\Delta x}{\Delta t} (W_x)_{i+\frac{1}{2},j}^{(n+\frac{1}{2})} (J_{y,p})_{i,j+\frac{1}{2}}^{(n+\frac{1}{2})} = (J_{y,p})_{i,j-\frac{1}{2}}^{(n+\frac{1}{2})} + q_s w_p \frac{\Delta y}{\Delta t} (W_y)_{j,i+\frac{1}{2}}^{(n+\frac{1}{2})}$$

Esirkepov, Comp. Phys. Comm. 135, 144 (2001)

The Finite-Difference Time-Domain (FDTD) method is a popular method for solving Maxwell's Equations



A. Taflove, Computation electrodynamics: The finite-difference time-domain method, 3rd Ed. (2005)

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Solving Ampère's equation: $\partial_t E_y = -J_y - \partial_x B_z$
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Solving Ampère's equation: $\partial_t E_y = -J_y - \partial_x B_z$

time-centering
$$\frac{(E_y)^{(n+1)} - (E_y)^{(n)}}{\Delta t} = -J_y^{(n+\frac{1}{2})} - (\partial_x B_z)^{(n+\frac{1}{2})}$$

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space-centering
$$\frac{(E_y)_i^{(n+1)} - (E_y)_i^{(n)}}{\Delta t} = -(J_y)_i^{(n+\frac{1}{2})} - \frac{(B_z)_{i+\frac{1}{2}}^{(n+\frac{1}{2})} - (B_z)_{i+\frac{1}{2}}^{(n-\frac{1}{2})}}{\Delta x}$$

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space-centering
$$\frac{(E_y)^{(n+1)}_i - (E_y)^{(n)}_i}{\Delta t} = -(J_y)^{(n+\frac{1}{2})}_i - \frac{(B_z)^{(n+\frac{1}{2})}_{i+\frac{1}{2}} - (B_z)^{(n-\frac{1}{2})}_{i+\frac{1}{2}}}{\Delta x}$$

Solving Faraday's equation: $\partial_t B_z = \partial_x E_y$

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Solving Ampère's equation: $\partial_t E_y = -J_y - \partial_x B_z$

time-centering
$$\frac{(E_y)^{(n+1)} - (E_y)^{(n)}}{\Delta t} = -J_y^{(n+\frac{1}{2})} - (\partial_x B_z)^{(n+\frac{1}{2})}$$
space-centering
$$\frac{(E_y)_i^{(n+1)} - (E_y)_i^{(n)}}{\Delta t} = -(J_y)_i^{(n+\frac{1}{2})} - \frac{(B_z)_{i+\frac{1}{2}}^{(n+\frac{1}{2})} - (B_z)_{i+\frac{1}{2}}^{(n-\frac{1}{2})}}{\Delta x}$$

Solving Faraday's equation: $\partial_t B_z = \partial_x E_y$

ing
$$\frac{(B_z)_{i+\frac{1}{2}}^{(n+\frac{3}{2})} - (B_z)_{i+\frac{1}{2}}^{(n+\frac{1}{2})}}{\Delta t} = \frac{(E_y)_{i+1}^{(n+1)} - (E_y)_i^{(n+1)}}{\Delta x}$$

space/time-centering

Numerical analysis of the FDTD solvers gives you access to the numerical dispersion relation & CFL condition

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The numerical electromagnetic wave equation in a vacuum

$$\partial_t^N \mathbf{E} = +\nabla^N \times \mathbf{B}$$
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The *numerical* electromagnetic wave equation in a vacuum Г

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The numerical electromagnetic wave equation in a vacuum

$$\begin{array}{l} \partial_t^N \mathbf{E} = +\nabla^N \times \mathbf{B} \\ \partial_t^N \mathbf{B} = -\nabla^N \times \mathbf{E} \end{array} \qquad \begin{array}{l} \partial_t^N F = \Delta t^{-1} \left[F^{(n+\frac{1}{2})} - F^{(n-\frac{1}{2})} \right] \\ \text{with:} \\ \partial_\mu^N F = \Delta \mu^{-1} \left[F_{i+\frac{1}{2}} - F_{i-\frac{1}{2}} \right] \end{array}$$

Using the standard technique to derive the wave equation leads to:

$$\partial_{tt}^{N}\mathbf{E} + \sum_{\mu} \partial_{\mu\mu}^{N}\mathbf{E} = 0$$

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Using the standard technique to derive the wave equation leads to:

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Looking for *numerical* solution in the form:

$$(E_y)_{i,j+\frac{1}{2},k}^{(n)} = E_{y0} \exp\left\{i\left[ik_x\Delta x + (j+\frac{1}{2})k_y\Delta y + kk_z\Delta z - n\omega\Delta t\right]\right\}$$

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After some algebra, one finds the *numerical dispersion relation*:

$$\frac{\sin^2\left(\omega\Delta t/2\right)}{\Delta t^2} = \sum_{\mu} \frac{\sin^2\left(k_{\mu}\Delta\mu/2\right)}{\Delta\mu^2}$$

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The FDTD solver is subject to *numerical dispersion* as the numerical light wave velocity is found to depend on its wavenumber and orientation.



A quick summary The PIC approach in a nutshell

Initializationtime step
$$n = 0$$
, time $t = 0$ Particle loading $\forall p$, define $(\mathbf{x}_p)^{n=0}$, $(\mathbf{u}_p)^{n=-\frac{1}{2}}$ Charge projection on grid $[\forall p, (\mathbf{x}_p)^{n=0}] \rightarrow \rho^{(n=0)}(\mathbf{x})$ Compute initial fields- solve Poisson on grid: $\left[\rho^{(n=0)}(\mathbf{x})\right] \rightarrow \mathbf{E}_{stat}^{(n=0)}(\mathbf{x})$ - add external fields: $\mathbf{E}^{(n=0)}(\mathbf{x}) = \mathbf{E}_{stat}^{(n=0)}(\mathbf{x}) + \mathbf{E}_{ext}^{(n=0)}(\mathbf{x})$ $\mathbf{B}^{(n=\frac{1}{2})}(\mathbf{x}) = \mathbf{B}_{ext}^{(n=\frac{1}{2})}(\mathbf{x})$

PIC loop: from time step n to n + 1, time $t = (n + 1) \Delta t$

Restart charge & current densities Save magnetic fields value (used to center magnetic fields)

 $\textbf{Interpolate fields at particle positions} \quad \forall p, \, [\mathbf{x}_p, \mathbf{E}^{(n)}(\mathbf{x}), \mathbf{B}^{(n)}(\mathbf{x})] \rightarrow \mathbf{E}_p^{(n)}, \mathbf{B}_p^{(n)}$

Push particles - compute new velocity $\forall p, \mathbf{p}_{p}^{(n-\frac{1}{2})} \begin{bmatrix} \mathbf{E}_{p}^{(n)}, \mathbf{B}_{p}^{(n)} \end{bmatrix} \mathbf{p}_{p}^{(n+\frac{1}{2})}$ - compute new position $\forall p, \mathbf{x}_{p}^{(n)} \begin{bmatrix} \mathbf{p}_{p}^{(n+\frac{1}{2})} \end{bmatrix} \mathbf{x}_{p}^{(n+1)}$

Project current onto the grid using a charge-conserving scheme

$$\left[\forall p \ \mathbf{x}_p^{(n)}, \mathbf{x}_p^{(n+1)}, \mathbf{p}_p^{(n+\frac{1}{2})}\right] \to \mathbf{J}^{(n+\frac{1}{2})}(\mathbf{x})$$

Solve Maxwell's equations

- solve Maxwell-Faraday:
$$\mathbf{E}^{(n)}(\mathbf{x}) \begin{bmatrix} \mathbf{J}^{(n+\frac{1}{2})(\mathbf{x})} \end{bmatrix} \mathbf{E}^{(n+1)}(\mathbf{x})$$

- solve Maxwell-Ampère: $\mathbf{B}^{(n+\frac{1}{2})}(\mathbf{x}) \begin{bmatrix} \mathbf{E}^{(n+1)}(\mathbf{x}) \end{bmatrix} \mathbf{B}^{(n+\frac{3}{2})}(\mathbf{x})$
- center magnetic fields: $\mathbf{B}^{(n+1)}(\mathbf{x}) = \frac{1}{2} \left(\mathbf{B}^{(n+\frac{1}{2})}(\mathbf{x}) + \mathbf{B}^{(n+\frac{3}{2})}(\mathbf{x}) \right)$

г

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 - numerical-Cherenkov can also plague simulation with relativistically drifting particles

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- High-performance computing: getting ready for the super-computers
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Large scale PIC simulation of magnetic reconnection at the earth magnetopause



Simulation box: $1280 \frac{c}{\omega_{pi}} \times 256 \frac{c}{\omega_{pi}}$ 25600×10240 PIC cells run up to $t = 800 \Omega_{ci}^{-1}$ $N_t \sim 9.5 \times 10^5$ timesteps for a total of 22×10^9 quasi-particles.

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Solution: share the work on 16384 CPUs !!!

Tianhe-2 **34 PF**: **17 MW**

Tianhe-2 34 PF: Exascale 1000 PF: 500 MW

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Parallelism*

massive hybrid MPI-OpenMP dynamic (load balance)

Memory

shared vs. distributed cache use

Vectorization**

Parallel I/O hdf5, openPMD

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*Derouillat *et al.*, Comp. Phys. Comm. **222**, 351 (2018) **Beck *et al.*, arXiv:1810.03949 Step 1: Parallelization PIC codes are well adapted to massive parallelism Step 1: Parallelization PIC codes are well adapted to massive parallelism

My Simulation (LWFA)



Step 1: Parallelization PIC codes are well adapted to massive parallelism

My Simulation (LWFA) $[\mu m]$ λ $x [\mu m]$


My Simulation (LWFA) y [µm] $x [\mu m]$ **Domain Decomposition**









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My Simulation (LWFA) 140 120 100 y [*μ*m] 80 60 40 20 00 20 100 40 60 80 $x [\mu m]$ **Domain Decomposition**

My Super-Computer CE computing element CE-0 CE-I MPI Message CE-2 CE-3 Passing Interface CE-4 CE-5 CE-6 CE-7

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My Simulation (LWFA)



----- Patch Decomposition























































Patches X coordinate



Patches X coordinate





Step 1: Parallelization Hybrid + Dynamic Load Balancing



Step 1: Parallelization Hybrid + Dynamic Load Balancing





- Scalar processing
 - traditional mode
 - one operation produces one result

SIMD processing

- with SSE / SSE2
- one operation produces multiple results





Beck et al., arXiv:1810.03949



Smart (particles) operators:

- interpolator, pusher, projector

Beck et al., arXiv:1810.03949



Smart (particles) operators:

- interpolator, pusher, projector

Smart (particles) data structures:

- beware random mem. access
- contiguous memory
- sort at all times!

Beck et al., arXiv:1810.03949

Step 2: Vectorization SMILEI uses an adaptive vectorization approach


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Step 2: Vectorization Laser-driven hole-boring



@ 32 PPC : speed-up x 1.5

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Step 2: Vectorization Weibel-mediated collisionless shocks



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A single particle goes through many $(N \gg 1)$ collisions at small angle θ which translates in a total deflection angle χ (not necessarily small)



for each pair (Monte-Carlo)

- compute the collision rate
- compute the deflection angle
- deflect one or both particles

Nanbu, Phys. Rev. E **55**, 4642 (1997); J. Comp. Phys. **145**, 639 (1998) F. Pérez et al., Phys. Plasmas **19**, 083104 (2012)

PIC codes are then able to treat purely collisional processes



J. Derouillat et al., *SMILEI: a collaborative, open-source, multi-purpose PIC code for plasma simulation,* to be submitted (available upon request)

Similarly field and collisional ionization can be treated using a Monte-Carlo approach

Field ionization of Carbon by a 5×10^{16} W/cm² 20 fs laser pulse

Stopping power of a cold aluminium plasma of density 10²¹ cm⁻³



R. Nuter *et al.*, Phys. Plasmas 18, 033107 (2011); F. Pérez et al., Phys. Plasmas 19, 083104 (2012)
J. Derouillat et al., *SMILEI: a collaborative, open-source, multi-purpose PIC code for plasma simulation,* to be submitted (available upon request)

Adding Quantum Electrodynamics (QED) effect is also very interesting for forthcoming multi-petawatt facilities

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Relativistically-Induced Transparency



Relativistically-Induced Transparency



E. Siminos et al., Phys. Rev. E 86, 056404 (2012)



E. Siminos et al., Phys. Rev. E 86, 056404 (2012)

Weibel instability in the presence of an external magnetic field



A. Grassi et al., Phys. Rev. E (in press)

2D and 3D simulations on super-computers will be necessary here

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High-harmonic generation & electron acceleration from laser-solid interaction



G. Bouchard, F. Quéré, CEA/IRAMIS

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A. Sävert et al., Phys. Rev. Lett. 115, 055002 (2015)

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M. Lobet et al., arXiv:1510.02301v2 (2015)

Plotnikov, Grassi & Grech, MNRAS

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Conclusions

- PIC codes are very popular, versatile & efficient tools for plasma simulation
- A large variety of physical problems can be addressed using PIC codes
- Additional physics modules can be implemented in PIC codes, but the physics cannot be scaled anymore (ω_r needs to be defined!)
- The PIC method is conceptually simple & can be efficiently implemented in a (massively) parallel framework
- Implementation on new & future architectures requires a strong input (co-development) from HPC specialists

Checkout SMILEI !!!

Code, Diagnostics/visualization tools and tutorials available online!



Smilei is a Particle-In-Cell code for plasma simulation. Open-source, collaborative, user-friendly and designed for high performances on super-computers, it is applied to a wide range of physics studies: from relativistic laser-plasma interaction to astrophysics.





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Publications



Tutorials

http://www.maisondelasimulation.fr/smilei

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